APOLLO LOGISTICS SUPPORT SYSTEMS MOLAB STUDIES

Task Report On

MOLAB Concept Evaluation Method

GPO PRICE Prepared under Contract No. NAS8-11096 by D. Ross Hard copy (HC) NORTHROP SPACE LABORATORIES **Space Systems Section** Microfiche (MF) 6025 Technology Drive Huntsville, Alabama

Ņ	65 12022	
2	(ACCESSION NUMBER)	(THRU)
O.	47	
Ĕ	(PAGES)	(CODE)
FAGILI	CR-61021	
-	(NASA CR OR THE OR AD NUMBER)	(CATEGORY)

For

NASA - GEORGE C. MARSHALL SPACE FLIGHT CENTER Huntsville, Alabama

APOLLO LOGISTICS SUPPORT SYSTEMS MOLAB STUDIES

Task Report On

MOLAB Concept Evaluation Method

by

D. Ross

Prepared under Contract No. NAS8-11096 by
NORTHROP SPACE LABORATORIES

Space Systems Section

6025 Technology Drive

Huntsville, Alabama

For
ADVANCED STUDIES OFFICE
PROPULSION AND VEHICLE ENGINEERING LABORATORY

This report is reproduced photographically from copy supplied by the contractor.

NASA-GEORGE C. MARSHALL SPACE FLIGHT CENTER

PREFACE

This report was prepared by the Northrop Space Laboratories, Huntsville Department, for the George C. Marshall Space Flight Center under authorization of Task Order N-29, Contract NAS8-11096. The NASA Technical Representatives were Mr. Charles R. Darwin and Mr. Jay Laue of the MSFC Propulsion and Vehicle Engineering Laboratory (R-P & VE-AB).

The work completed was a ten man-week effort commencing on 8 June 1964 and ending 21 August 1964. The data and methods presented herein are intended as a guide to aid in the technical evaluation and selection of a MOLAB concept.

NOTICE

This report was prepared as an account of Government sponsored work. Neither the United States, nor the National Aeronautics and Space Administration (NASA), nor any person acting on behalf of NASA:

- A.) Makes any warranty or representation, expressed or implied, with respect to the accuracy, completeness, or usefulness of the information contained in this report, or that the use of any information, apparatus, method, or process disclosed in this report may not infringe privately owned rights; or
- B) Assumes any liabilities with respect to the use of, or for damages resulting from the use of any information, apparatus, method or process disclosed in this report.

As used above, "person acting on behalf of NASA" includes any employee or contractor of NASA, or employee of such contractor, to the extent that such employee or contractor of NASA, or employee of such contractor prepares, disseminates, or provides access to, any information pursuant to his employment or contract with NASA, or his employment with such contractor.

TABLE OF CONTENTS

			Page
1.0	INTR	ODUCTION	1
2.0	CONC	CEPT EVALUATION OBJECTIVES	2
3.0	CONC	CEPT EVALUATION AND COMPARISON CRITERIA	3
	3.1	SYSTEM RATING CRITERIA	3
	3.2	MOLAB RATING CRITERIA	6
	3.3	SYSTEM SUMMARY SHEET	6
4.0	CO NC	CLUSIONS AND RECOMMENDATIONS	9

SECTION 1.0

INTRODUCTION

The NASA Manned Lunar Exploration Program has as its objective the scientific investigation of the moon. The Apollo project is the first approved effort in this program and has as its specific objective the landing of two astronauts on the moon and their safe return to earth within this decade.

The Apollo Logistic Support System (ALSS) is being considered for use in conjunction with Apollo missions. Its broad objective is to assure: maximum scientific benefits from lunar exploration, crew stay-time extension, crew safety during these operations and the safe return of the astronauts to earth.

A Manned Lunar Surface Mobile Laboratory Vehicle called MOLAB has been proposed for accomplishing these objectives and is now being studied by MSFC, both with respect to mission definition and investigations of supporting technologies. During the course of the MOLAB concept studies, several concept designs have been produced. These concepts differ in configuration, internal volume, internal and external arrangement and performance characteristics. All of the concepts have the capability of performing the presently defined scientific mission for the MOLAB.

This task is an endeavor to establish a model with which to technically evaluate the various design concepts. The concept parameters considered are: crew safety, reliability, design simplicity, lunar terrain negotiability, performance efficiency, weight, development risk, weight and cost. These parameters are considered for the stowage, deployment, dormant and operational phases of the mission.

SECTION 2.0

CONCEPT EVALUATION OBJECTIVES

The objective of this evaluation model is to establish a matrix of the pertinent technical parameters of a MOLAB along with a numerical grading scheme which includes factors for item and system importance and system redundancy. This matrix is the model which the evaluator uses in assessing the merits of a system or subsystem with a number as the end result. The sum of all the subsystem and system numbers is the evaluation merit number for the concept.

The establishment of the pertinent technical parameters for this matrix is the most difficult part of this task. The technical parameters, which we shall call items, should be general enough to apply to any design concept. A sub-matrix will be established for the MOLAB and for each system of the MOLAB using the breakdown as established by the "MOLAB Payload Mass Format", no date or document number, issued by MSFC R-P & VE-AB. This will allow comparison of the systems of the various concepts on a common format basis.

Each system evaluation matrix will consider the following general parameters in addition to those parameters which are peculiar to a particular system.

- 1. Power Requirements.
- 2. Reliability Assessment.
- 3. Performance Parameters
- 4. Simplicity of Design.
- 5. Weight, Total MOLAB and individual systems.
- 6. Development risk, time frame for.
- 7. Cost

When the parameters are not sufficently defined it will be necessary for the evaluator to make an assessment of the probable value.

SECTION 3.0

CONCEPT EVALUATION AND COMPARISON OUTLINE

3.1 SYSTEM RATING CRITERIA

The method which is proposed to evaluate the previously discussed matrices is a numerical grading system. This system uses the numerals of "0" (zero) through "10" (ten) in accordance with the degree of design excellence. In addition to the numerical grade factor an importance factor for the item is applied to denote the relative importance of the item to the system of which it is a part. This importance factor is a multiplier for the item grade factor, the product is the item grade.

An importance factor is also assigned to each MOLAB system, This factor indicates the importance of the system to the safety of the astronauts and the consequent mission success, i.e., the communication system failure would not be as serious as would a power system failure, or an environmental control system failure. The importance factor is used as a multiplier for the system grade.

In addition to the system importance factor, a redundancy factor is also applied to each system. This factor is applied by the evaluator as a measure of redundancy that the system contains, i.e., the electric power system may have 3 or 4 individual and separately supplied fuel cells in addition to a backup storage battery. This system could be considered fully redundant and would receive a high redundancy factor rating. This factor is used as a multiplier for the product of the system grade and the importance factor.

In summary, each system of the MOLAB is graded by its design excellence factor, item importance factor, system importance factor and redundancy factor. The equation for the system grading would be

$$Gs = \left(\begin{array}{cc} \sum_{i=1}^{n} & Ef_{i} & If_{i} \\ \hline & 1 & \\ \hline & n & \end{array}\right) Sf \quad Rf$$

 G_s = System Grade

E_f = Design Excellence Grade Factor

I_f = Item Importance Factor

n = Number of Items

 S_f = System Importance Factor

 $R_f = Redundancy Factor$

Grade Facto. Values:

A Item Importance Factor:

The item importance factor applies to each item listed and is chosen by the evaluator and represents his assessment of the relative importance of each item to the system being evaluated.

- 2 = Least Important 4 = Less Important
- 6 = Important
- 8 = More Important 10 = Very Important

B Grade Factor:

The grade factors are chosen by the evaluator and represent his assessment of the design excellence of each item.

- 0 = Item is not included in the concept = No Grade.
- l Poor
- 2 = Fair
- 3 = Good
- 4 = Very Good
- 5 = Excellent

C System Importance Factor

The system importance factor is applied to each system and is used as a multiplier. To the system Grade. The system importance factor chosen depends upon the evaluators judgement of the MOLAB mission impairment, expressed in percent, if that system became inoperative. This establishes the relative importance of the system to other MOLAB systems and provides a multiplier for equalization of the system grades based on system importance.

D Redundant Factor:

The redundant factor is applied to each system of the MOLAB and represents the evaluators judgement of the amount of redundancy a particular system contains.

- 1.0 = System has no redundancy.
- 1.10 = System has redundant characteristics*
- 1.25 = System has designed critical redundancy.
- 1.50 = System has full designed redundancy.
 - * Redundant characteristics means that the system has redundant capabilities by nature of its design but not planned as such, i.e., the mobility system may have traction motors in each wheel, if one malfunctioned the other three could provide mobility.

REDUNDANT FACTOR IMPORTANCE FACTOR ITEM GRADE GRADE ASSESSMENT METHOD ITEM ITEM DESCRIPTION GRADE TOTAL: _. GRADE = (GRADE TOTAL) + (Nº. OF ITEMS) : _ _ _ (GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR): _ _ _

PAGE NO._

The form to be used for the system matrix is shown as a blank form in Figure 1. The name of the system is to be shown on the dashed line at the top of the page. The system importance factor will appear in the block in the upper right hand corner of the form. The redundant factor will be entered in the block just above the importance factor. The system items will be listed in the item description blocks. The assessment method blocks will show the source of the data used for evaluation of the item. Enter the item factor determined for the item in the item factor block. Enter the grade factor determination in the grade factor block. Multiply the item factor by the grade factor and enter the product in the grade block. Add the grades of the items and enter the sum in in the grade total line in the lower right hand corner of the form. Divide the grade total by the number of items graded and enter in next lower line. Multiply this line by the product of the importance factor X the redundant factor and enter on the next lower line. This represents the system grade. A complete set of MOLAB system forms with suggested items, filled in is included elsewhere in this report.

3.2 CONCEPT RATING CRITERIA

There are many aspects of the completely assembled and integrated concept which require evaluation. These parameters in general, are: performance, reliability, integration, weight and cost. Forms are provided for this evaluation matrix, a blank form is shown in Figure 2. This form is similar to the forms for systems except for the system importance factor and the redundancy factor blocks, these factors are not applicable for a concept evaluation. The blocks for item description, assessment method, item factor, grade factor and grade are the same and use the same factors as used for the system grading sheet shown on Figure 1. The sum of the item grades is divided by the number of items to obtain the concept grade.

A complete set of MOLAB concept evaluation forms with suggested items filled in is included elsewhere in this report.

3.3 SYSTEM SUMMARY

A system summary sheet (Figure 3) has been provided for entering the scores and pertinent data taken from the system rating sheet (Figure 1) and the concept rating sheet (Figure 2). The sum of these ratings is the concept comparison rating and can be used to select a design concept.

CONCEPT RATING SHEET

PAGE Nº .____

ITEM	ITEM	DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	ITEM GRADE
1						
2						
3						
4						
5						
6						
7					·	
8						
9						
10						
11						·
12						
.13						
14						
15						·
16						
17		· · · · · · · · · · · · · · · · · · ·				
18						
19						
20						

•	ITEM GRADE TOT	
GRADE = (GRADE	TOTAL) - (Nº OF ITE	EMS):

PAGE	N (O		
	172	 	

ITEM	SYSTEM	IMPORT.	GRADE	RATING
1				
2				
3				
4				
5				
E				
7				
8				
9				
10				
11				
12				
13				
14	,			
15				
16				
17				
18				
19				
20				

CONCEPT COMPARISON RATING:____

SECTION 4.0

CONCLUSIONS AND RECOMMENDATIONS

4.1 CONCLUSIONS

A matrix of approximately 500 technical items has been assembled for the evaluation of the various systems including items of the operational MOLAB. An attempt was made to keep these items as general in nature as possible, in some instances this was not considered adequate to properly evaluate the system, in those cases the items are of a more specific nature.

The systems breakdown follows the "MOLAB Payload Mass Format" with the exception of the "cabin System" which begins with 1.2 for the "Structural Subsystem", this matrix lists this subsystem 1.1. The subsequent subsystems are all one digit less for the "Cabin System". All of the other systems are per the mass format numbering system.

This matrix does not endeavor to cover every parameter of each system but does endeavor to cover some of the major technical para - meters of each system. The matrix as presented herein along with the method of grading and represents a system which will accomplish a general evaluation of the MOLAB and the systems which make up the MOLAB.

4.2 RECOMMENDATIONS

It is recommended that the various system groups evaluate the systems of the concept studies for which they are responsible. These groups have the technical background necessary to intelligently make an evaluation. This will eliminate some of the prejudices which would exist if one person attempted to evaluate all of the systems.

The matrix herein which was generated for this task should be upgraded and expanded as system requirements and operational environments become better defined. The more parameters that are analyzed the more accurate an evaluation becomes.

1.1

PAGE NO. __.

1 Cal 2 Str 3 Str 4 Pre Ass 5 Pre Ass 6 Cal Ass	ITEM DESCRIPTION bin Structure Simplicity Assessment ructure Load Path Simplicity Assessment ructure Rigidity Assessment essure Vessel Shape Efficiency sessment essure Vessel Shock Load Efficiency sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration	REDUNDA IMPORTANA ASSESSMENT METHOD	CE FA	-	GRADE
1 Cal 2 Str 3 Str 4 Pre Ass 5 Pre Ass 6 Cal Ass 7 Cal	bin Structure Simplicity Assessment ructure Load Path Simplicity Assessment ructure Rigidity Assessment ressure Vessel Shape Efficiency ressure Vessel Shock Load Efficiency response to the Structure Simplicity Assessment results of the	ASSESSMENT METHOD	ITEM	GRADE	GRADE
1 Cal 2 Str 3 Str 4 Pre Ass 5 Pre Ass 6 Cal Ass 7 Cal	bin Structure Simplicity Assessment ructure Load Path Simplicity Assessment ructure Rigidity Assessment ressure Vessel Shape Efficiency ressure Vessel Shock Load Efficiency response to the Structure Simplicity Assessment results of the	METHOD		GRADE FACTOR	GRADE
2 Str 3 Str 4 Pre Ass 5 Pre Ass 6 Cat Ass 7 Cat	cucture Load Path Simplicity Assessment essure Vessel Shape Efficiency sessment essure Vessel Shock Load Efficiency sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration	nt			
3 Str 4 Pre Ass 5 Pre Ass 6 Cat Ass	essure Vessel Shape Efficiency sessment essure Vessel Shock Load Efficiency sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration	nt			
4 Pre Ass 5 Pre Ass 6 Call Ass 7 Call	essure Vessel Shape Efficiency sessment essure Vessel Shock Load Efficiency sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration				
5 Pre Ass 6 Cab Ass 7 Cab	sessment essure Vessel Shock Load Efficiency sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration				
6 Cab Ass	sessment bin Thermal Insulation Efficiency sessment bin Micro-Meteoroid Penetration				
7 Cab	sessment bin Micro-Meteoroid Penetration				
7 Cab	oin Micro-Meteoroid Penetration				
	iciency Assessment		,		
	oin Volume Adequacy Assessment				·
9 Floo	or to Ceiling Height Adequacy				
10 Cab	oin Materials Compatibility with nar Environment		•		
II Cab Isol	oin Structural Attachments Thermal lation Efficiency Assessment				
12 Cab Isol	oin Equipment Appendages Thermal Lation Efficiency Assessment				
13 Min Req	nimum Press. Vessel Penetrations				
14 Cab	oin Weight/Unit Volume Efficiency				
Dep.	oins Ability to perform during Stowage loyment, Dormant & Operation				
	elopment Risk Assessment				
17 Tota	al Power Requirement Assessment				
18 Weig	ght Assessment				
19 Cost	t Assessment				
20					

,	GRADE	TOTAL:
GRADE=(GRADE	TOTAL) + (Nº. OF I	TEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTANCE	E FACTOR):

1.2

PAGE Nº _____

CABI	N SYSTEM - AIR LOCK	REDUNDA	NI FA	CIUK	
		IMPORTANI	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Airlock Structure Simplicity Assessment		·		
, 2	Structure Load Path Simplicity Assessment				
3	Airlock Volume Adequacy Assessment			,	
4	Floor to ceiling height adequacy				
5	Outer door design simplicity Assessment				
<u>ن</u>	Outer Door seal simplicity Assessment				
7	Outer Door Locking Adequacy Assessmen				
8	Inner Door Design Simplicity Assessment				
9	Inner Door Seal Simplicity Assessment				
. 10	Inner Door Locking Adequacy Assessment	•			
11	Airlock/Cabin Volume Utilization Efficence Assessment	y			
12	Pumping Power Requirement Assessment	-			
13	Pumping Equipment Weight Assessment				
14	Materials Compatibility with Lunar Environment				
15	Ability to Perform Entire Mission Assess	ment			
16	Development Risk Assessment				
17	Thermial Isolation Effectiveness				
18	Total Power Requirement Assessment			(
19	Weight Assessment				
20	Cost Assessment				

GRADE TOTAL: ____ GRADE = (GRADE TOTAL) ÷ (Nº. OF ITEMS): ____ (GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR): ____

1 3

PAGE Nº ____

<u>CAB</u>	CABIN SYSTEM - DOCKING ADAPTER		NT FA		
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
-	Structure Simplicity	·			·
2	Structure Load Path Simplicity				
3	Internal Volume Utilization Efficency				
4	Hatch Design Simplicity				
5	Hatch Seal Adequacy				
6	Emergency Exit Capability (Space Suit)				
7	CM Access To IMU Adequacy				
8	CM Access To MOLAB Adequacy				
9	Ability To Perform Entire Mission				
10	Thermal Isolation Effectiveness				- 1
11	Development Risk Assessment				
12	Materials Compatibility with Lunar Environment			·	
13	Weight Assessment				·
14	Cost Assessment				
15	Total Power Requirement Assessment				
16					
17					
18					
19					
20					
		GPADE	エヘナ	^	

GRADE TOTAL:
GRADE = (GRADE TOTAL) + (Nº. OF ITEMS) :
(GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

1.4

PAGE Nº ____

CAB	IN SYSTEM - VIEWING PORTS	REDUNDA	NT FA	CTOR	
رسيدي		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
	Structure Simplicity				·
2	Structure Load Path Simplicity				
3	Field Of Vision Adequacy	-			,
4	Port Area/Field of Vision Ratio				
5	Port Mounting Thermal Isolation Adequacy				
Ø	Port Micro-Meteoroid Protection Adequac	у			
7	Radiation Stability of Port Materials				
æ	Redundancy In Multiple Forts		(
9	Redundancy In Other Optical Methods				
10	Materials Compatibility With Lunar Environment				
11	Development Risk Assessment				
12	Ability To Perform Entire Missions				·
13	Port Electromagnetic Transmission Characteristics.				
14	Port Brightness Control Characteristics				
15	Port Seal Adequacy				
16	Weight Assessment				
17	Cost Assessment		,		
lġ.	Total Power Requirement Assessment				
19					
20					
		50 1 00		^	

	GRADE	TOTAL:
GRADE=(GRADE	TOTAL) + (Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTÓR):

1.5

PAGE Nº.____

CABIN SYSTEM - CONTROLS & DISPLAY		NT FA	CTOR	
		CE FA	CTOR	
ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
Controls Arrangement, Simplicity				
Controls Arrangement, Convenience	,			
Space Suit Operation Compatibility				
Controls Identification Ease Assessment				
Dual Operation Capability Assessment				
Control Operational Room Assessment				
Automatic Control Capability Adequacy				
Automatic Overide Capability				
Displays/View Port Relation Assessment				
Displays Arrangement Organization				
Display Illumination Controllability Assessment				
Display Eye Accommodation Assessment				
Display/Controls Relation Assessment				
Display, Malfunction Alarm Capability				
Materials Compatibility With Lunar Environment	•		·	
Total Power Requirement Assessment	·			
Weight Assessment				
Cost Assessment				
				•
	Controls Arrangement, Simplicity Controls Arrangement, Convenience Space Suit Operation Compatibility Controls Identification Ease Assessment Dual Operation Capability Assessment Control Operational Room Assessment Automatic Control Capability Adequacy Automatic Overide Capability Displays/View Port Relation Assessment Displays Arrangement Organization Display Illumination Controllability Assessment Display Eye Accommodation Assessment Display/Controls Relation Assessment Display, Malfunction Alarm Capability Materials Compatibility With Lunar Environment Total Power Requirement Assessment Weight Assessment	ITEM DESCRIPTION ASSESSMENT METHOD Controls Arrangement, Simplicity Controls Arrangement, Convenience Space Suit Operation Compatibility Controls Identification Ease Assessment Dual Operation Capability Assessment Control Operational Room Assessment Automatic Control Capability Adequacy Automatic Overide Capability Displays/View Port Relation Assessment Displays Arrangement Organization Display Illumination Controllability Assessment Display Eye Accommodation Assessment Display, Malfunction Alarm Capability Materials Compatibility With Lunar Environment Total Power Requirement Assessment Weight Assessment	ITEM DESCRIPTION ASSESSMENT ITEM METHOD FACTOR Controls Arrangement, Simplicity Controls Arrangement, Convenience Space Suit Operation Compatibility Controls Identification Ease Assessment Dual Operation Capability Assessment Control Operational Room Assessment Automatic Control Capability Adequacy Automatic Overide Capability Displays/View Port Relation Assessment Displays Arrangement Organization Display Illumination Controllability Assessment Display Eye Accommodation Assessment Display/Controls Relation Assessment Display, Malfunction Alarm Capability Materials Compatibility With Lunar Environment Total Power Requirement Assessment Weight Assessment	ITEM DESCRIPTION ASSESSMENT ASSESSMENT ACTOR Controls Arrangement, Simplicity Controls Arrangement, Convenience Space Suit Operation Compatibility Controls Identification Ease Assessment Dual Operation Capability Assessment Control Operational Room Assessment Automatic Control Capability Adequacy Automatic Overide Capability Displays/View Port Relation Assessment Displays Arrangement Organization Display Illumination Controllability Assessment Display Eye Accommodation Assessment Display, Malfunction Alarm Capability Materials Compatibility With Lunar Environment Total Power Requirement Assessment Weight Assessment

	•	GRADE	TOTAL:
	GRADE=(GRADE	TOTAL) + (Nº. OF I	TEMS):
((GRADE)'X (REDUNDANT	FACTOR × IMPORTANCE	E FACTOR):

1.6

PAGE Nº ____

CABIN SYSTEM - CREW SYSTEMS REDUNDA		NT FA	CTOR		
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Recumbent Sleeping Position (S) Adequacy				
2	Erect Standing Position Adequacy				
3	Gymnastic Equipment Adequacy				
4	Personel Hygiene Facilities Adequacy				
5	Toilet Adequacy Assessment				•
Ø	Waste Disposal, Human & Non-Human Adequacy				=
7	Food, Water & Preparation Adequacy				٠
8	Medical Instru & Literature Adequacy				·
ġ	Medical Supplies & Drugs Adequacy				·
10	Interior Lighting Adequacy (All Tasks)				
11	Interior Thermal Control Adequacy				
12	Atmospheric Constituants Cont. Adequacy				
13	Auditory Noise Level Control Adequacy				
14	Materials Compatibility With Lunar Environment				
15	Ability To Perform Entire Mission				
16	Development Risk Assessment				
17	Weight Assessment				
18	Cost Assessment				
19	Total Power Requirement Assessment				
20					

	GRADE TOTAL:	
	GRADE=(GRADE TOTAL)+(Nº. OF ITEMS):	
((GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):	_

1.7

PAGE Nº._____

CABIN SYSTEM - ENVIRONMENTAL CONTROL SYS. IMPORTANCE FACTOR

		INII OK I AIOU	<u> </u>	CIOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Capability Of Maintaining O ₂ (Essentially 1 Atmosphere of 5.0 PSIA	Pure)			
2	Capability of Maintaining 3.5 PSIA for Emergency Assessment	·			
3	Cabability of Making UpO2Lost By 56 Airlock Cycles / Mission				
4	Odor & Noxious Gas Removal Adequacy				
5 ·	Caribon Dioxide Removal Adequacy				
6	Internal Thermal Control Capacity				
7	Equip. Thermal Control Adequacy				
8	Humidity Control Adequacy				
9	Emergency Capability Adequacy				
10	Back Pack Re-Fill Capability				
11	Interior & Exterior Suit Umbilical Adequa	y			
12	Suit Thermal Control Capability				
13	Servicing ECS Simplicity				
14	Materials Compatibility with Lunar Environment				
15	Ability to Perform Entire Mission				
16	Development Risk Assessment	.			
17	Heat Rejection Capability (Lunar Noon)				
18	Weight Assessment	,			
19	Cost Assessment				
20	Total Power Requirement Assessment				

	GRADE TOTAL:
	GRADE=(GRADE TOTAL)+(Nº OF ITEMS):
((GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

PAGE Nº .____

мові	LITY SYSTEM - CHASSIS	REDUNDA	NT FA	CTOR	
		IMPORTAN	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
ĺ	Structural Simplicity Assessment				
2	Load Path Simplicity Assessment		·		
3	Structure Rigidity Assessment				
4	Adequate Chassis / Cabin Thermal Isolation Assessment				·
5	Cabin Supports Simplicty Assessment	·			
6	Tiedown Support Hard Point Provisions Adequacy				
7	Equipment Support Hard Point Provisions Adequacy				
8	Suspension System Mounting Hard Point Provisions Adequacy				
9	Load Handling Capability, For All Mission Phases Loads, Adequacy				
10	Compatibility of Materials With Lunar Environment				
11	Ability to Perform Entire Mission				
12	Development Risk Assessment				
13	Weight Assessment				
14	Cost Assessment	·		<u>.</u>	
15	Total Power Requirement Assessment	·	·		
16					
17	,				
81					,
19					
20					
		50105			

		101AL:
GRADE = (GRADE	TOTAL) + (Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTANCE	CE FACTOR):

2.2

PAGE Nº.___

MOB	ILITY SYSTEM - CRYOGENIC STORAGE	REDUNDA	NT FA	CTOR	
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
ſ	Optimum Tank Isulation Provision For 180 Days Dormant + 14 Days Operation	nal			
2	Vacuum Jacket Provisions Adequacy				
3	Optimum Storage Pressure Capability				
4	Optimum Vent Pressure Capability	·			
5	Tank Mounting Structure Adequacy				
6	Micro-Meteoroid Protection Adequacy				
7	Tank Refill & Topping Provisions				
8	Plumbing & Control Sys. Adequacy				
9	Service & Repair Accessability				
10	Activation & Deactivation Capability				
11	Materials Compatibility with Lunar Environment				
12	Ability to Perform Entire Mission				
13	Development Risk Assessment				
14	Weight Assessment	·			
15	Cost Assessment	·			
16	Total Power Requirement Assessment				
١7					
18					
19		`			
20					
		CRADE		A	

	GRADE TOTAL:
	GRADE=(GRADE TOTAL)+(Nº. OF ITEMS):
((GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

2.3

PAGE Nº.___

MOBII	ITY SYSTEM - DRIVE MECHANISM	REDUNDA	NT FA	CTOR	
1477.171.17		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Optimum HP/RPM Ratio 14 Day Mission		·		
. 2	Optimum Gear Reduction Efficency	·			
3	Minimum No. Mechanical Active Seals			,	
4	Optimum Vehicle Propulsion Efficency				
5	Optimum Power Conditioning for Efficent Speed Control				
6	Heat Rejection Adequacy	·		·	
7	Cold Operational Provisions Adequacy				
8	Lubrication Provisions Adequacy			٠.	
. 9	Vacuum Operational Adequacy				
10	Fail Safe Provisions Adequacy				
11	Materials Compatibility With Lunar Environment				
12	Ability to Perform Entire Mission				
13	Development Risk Assessment				
14	WT/HP Ratio Of Drive Mechanism				
15	Weight Assessment				
16	Cost Assessment				
17	Total Power Requirement Assessment				
18					
19					
20					

	GRADE TOTAL:
	GRADE=(GRADE TOTAL)+(Nº. OF ITEMS):
(GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

2.4

PAGE Nº ____

MOBILITY SYSTEM - WHEEL ASS'Y REDUNDANT FACTOR					
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
1	Wheel Diameter Suitability				
2	Effective Wheel Dia. Adequacy				
3	Wheel Rolling Radius Suitability				
4	Torsional Rigidity Adequacy				
5	Lateral Rigidity Adequacy				
6	Wheel Spring Rate Suitability				
7	Optimum Tread Width	,			
8	Foot Print Area Adequacy, Hard Surface				
9	Wearing Surface Adequacy for Mission				
10	Materials Compatibility with Lunar Environment				
11	Ability to Perform Entire Mission				
12	Floatation Characteristics on Weak Soils				
13	Development Risk Assessment				
14	Weight Assessment				
15	Cost Assessment				
16	Total Power Reqirement Assessment				
17					
18					
19					
20					

	GRADE TOTAL:	-
	GRADE=(GRADE TOTAL)+(Nº. OF ITEMS):	
((GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):	_

2.5

PAGE Nº _____

MORII	LITY SYSTEM - SUSPENSION ASS'Y	REDUNDA	NT FA	CTOR	
	<u> </u>	IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Linkage Geometry Assessment				
2	Spring Rate Assessment				
3	Spring Efficency Assessment				
4	Dampening Characteristics Assessment		-	·	
5	Alignment Adequacy Assessment				
6	Design Simplicity Assessment		,		
7	Fail Safe Characteristics Assessment				
8	Materials Compatibility With Lunar Environment		(
9	Development Risk Assessment				
10	Weight Assessment				
11	Cost Assessment				
12	Total Power Requirement Assessment				
13	Suspension Reliability Assessment	,			
14					
15					
16					
17					
ાઇ					
19					
20					
		GRADE	707	<u> </u>	

	GRADE	TOTAL:
GRADE=(GRADE	TOTAL) + (Nº. CF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTANT	CE FACTOR):

3.1

PAGE Nº.__

POW	ER SYSTEM - PRIMARY POWER	RECOUNDA	14 I A	CIUR	<u></u>
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Power Source Reliability Assessment				í
2	Powersource Efficency Assessment				
3	Power Source Simplicity				
4	Usable Water Production Capability				
5	Operation Capability in Lunar Environmen			٠	
Ø	Compatibility with Other Systems				,
7	Efficent Throttling Characteristics				•
8	Inertial Effect on Molab Assessment				
9	Min. Conversion Phases from Fuel to Pow	er			
10	Min. Power Conditioning Requirements				,
11	Materials Compatibility with Lunar Environment				
12	Development Risk Assessment				
13	Weight Assessment				
14	Cost Assessment				
15	Activation Cycling Assessment				
16	Total Power Requirements for Cell Oper. & Maint. Assessment				
17					
18					
19					
20					
		-5.5			

		TOTAL:
GRADE=(GRADE	TOTAL)+(Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

3.2

POWER SYSTEM - SECONDARY POWER		REDUNDA	NT FA	CTOR	<u> </u>
		IMPORTANI	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
1	Power Source Reliability Assessment				,
2	Power Source Efficency Assessment				
3	Power Source simplicity				
4	Operational Capability in Lunar Environ				
5.	Compatibility with Other Systems				
6	Efficent Throttling Characteristics				
7	Inertial Effect on Molab Assessment				
8	Min. Conversion Phases from Fuel to Po-	wer			
9	Min. Power Conditioning Requirements				
10	Materials Compatibility with Lunar Environment				
11	Development Risk Assessment				
12	Weight Assessment				
13	Cost Assessment				
14	Activation Cycling Assessment				
15	Total Power Requirement for sys. Oper. and Maint. Assessment.				
16					
17					
18					
19					
20					
					·

	GRADE TOTAL:
	GRADE = (GRADE TOTAL) + (Nº. OF ITEMS) :
((GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

3.3

PAGE Nº ____

POWER SYSTEM - AUXILIARY POWER		REDUNDA	NT FA	CTOR	
			CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
1	Power Source Reliability Assessment	ŕ			
2	Power Source Efficency Assessment				
3	Power Source Simplicity Assessment				
4	Operational Capability in Lunar Environm	ent			
5	Compatibility with Other Systems				
. 6	Efficent Throttling Characteristics			•	
7	Inertial Effects on MOLAB Assessment				
8	Min. Conversion Phases from Fuel to Pow	er			
9	Min. Power Conditioning Requirements				
10	Materials Compatibility with Lunar Environment				
11	Activation Cycling Assessment				
12	Development Risk Assessment				
13	Weight Assessment				
14	Cost Assessment				
15	Total Power Requirement for Sys. Oper. and Maint. Assessment				
16					
۱7					
18					
19					
20					

	GRADE TOTAL:
	GRADE=(GRADE TOTAL) + (Nº. OF ITEMS):
(GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

3.4

PAGE Nº .__

POWE	R SYSTEM- POWER DISTRIBUTION	REDUNDA	NT FA	CTCR	<u></u>
		MPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD		GRADE FACTOR	GRADE
1	Distribution Reliability Assessment				
2	System Efficency Assessment				
3	System Simplicity Assessment				
4	Operational Capability in Lunar Environment				
5	Compatibility with Other Systems				
6	Conversion Equip. Reliability Assessment				
7	Conversion Equip. Efficency. Assessment		-		
8	Control Equip. Reliability Assessment				
9	Control Equip. Efficency Assessment				
10	Operational Degradation Assessment				
11	Service & Repairability Assessment				
12	Development Risk Assessment				
13	Weight Assessment				
14	Cost Assessment				
15	Total Power Requirement for Sys. Supervision & Maint. Assessment				
16					
17					
18.					,
.19					
20	·				
		CRADE	7:07:	1	

	GRADE	TOTAL:
GRADE GRADE	TOTAL)+(Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTANCE	CE FACTOR):

3.5

PAGE Nº .___

POW]	ER SYSTEM - HEAT DISSIPATION	REDUNDA	NT FA	CTOR	
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
í	System Reliability Assessment				
,2	Emissivity Efficency, Lunar Noon				
3	System Efficency Assessment				
4	System Simplicity Assessment				
5	System Adequacy for Entire Mission				
6	Compatability with Other Systems Assessment				
7	Pumping Equipment Adequacy				
8	Control Equipment Adequacy				
9	Development Risk Assessment				
10	Meteoroid Damage Assessment	į			
11	Weight Assessment				
12	Cost Assessment				
13	Total Power Requirement Assessment				
14					
15					
16	,				
17					
18					í
19					-
20					
					

		101AL
GRADE=(GRADE	TOTAL) + (Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

4.1

PAGE Nº.__.

ASTRIONICS SYSTEM-NAVIGATION & GUIDANCE REDUNDANT FACTOR					
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
ſ	Remote Operation Mode (Unmanned) Accuracy Assessment (Unloading)				
2	Remote operation mode (Unmanned) Accuracy Assessment (Lunar Traveres)				
3	Manned Operation Mode, Circle of Error, Probable Position Determination Error	·			
4	Odometer, Sensor Accuracy				
5	Vehicle Attitude Sensor Accuracy				
6	Gyro Azimuth Sensor Accuracy				
7	Speedometer Sensor Accuracy	•			
8	Astro-Sextant Adequacy				
9	Optical Transit Adequacy			•	
10	Guidance Computer Adequacy				
11.	Guidance Controller Adequacy				
12	System Reliability Assessment				
13	Compatibility with other Systems				
14	Service & Repairability Assessment				
15	Materials Compatibility with Lunar Envir	onment			
16	Development Risk Assessment				
17	Weight Assessment				
18	Cost Assessment				
19	Total Power Requirement Assessment				
20					

	GRADE TOTAL:
	GRADE=(GRADE TOTAL)+(Nº. OF ITEMS):
((GRADE) × (REDUNDANT, FACTOR × IMPORTANCE FACTOR):

4.2

PAGE NE ____

ASTRI	ONICS SYSTEM - COMMUNICATIONS	REDUNDA	NT FA	CTOR	L
		IMPORTAN	CE FA	CTOR	
ITEM		ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	<u>UHF Transm. To DSIF</u> & Apollo Net During Operation, Capability Assessment				
2	UHF Command Capability During Dormant Period, Capability Assessment				
3	UHF Transmission (Telem) During Dorman Period, Capability Assessment				
4	UHF & VHF Video Transmission During Dormant & Manned Phases Assessment				
5	Comm. System Compatability with RFI & EMI, Assessment				
6	Homing Capability Assessment		ŕ		-
7	Comm. System/ Astronaut interface Compatibility Assessment				
8	St'd Electronic Packaging Adequacy Asses	sment	(
9	Service & Maintainability Assessment				
10	Materials Compatibility with Space				
11	Development Risk Assessment				
12	Weight Assessment				
13	Cost Assessment				
14	Total Power Requirement Assessment				
15		_			
16					
17					
18					
19					
20					
		CRADE			

,	GRADE TOTAL:
GRADE=(GRADE TOT	AL)+(Nº. OF ITEMS);
(GRADE) × (REDUNDANT FAC	TOR X IMPORTANCE FACTOR):

4.3

PAGE Nº.___

ASTRI	ONICS SYSTEM - ELECTRONICS	REDUNDA	NT FA	CTOR	
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTUR	GRADE FACTOR	GRADE
1	Automatic Checkout sys. Elect mnics Assessment				
2	Auto. Checkout sys. Capability Assessment				
ر	Auto. Checkout sys. instrumentation Adequacy Assessment				
4	Leak Detection Sys. (Cabin) Electronics Adequacy Assessment	·			
5	Development Risk Assessment			e.	
Ø	Total Power Requirement Assessment				
7	Weight Assessment				
8	Cost Assessment				
9					
10					
11					
12					
13	•				
14					
15					
16					
17					
18					
19					
20					
		CPADE	7.07.	<u> </u>	

			TOTAL:
	GRADE=(GRADE	TOTAL) - (Nº . OF	ITEMS):
((GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

PAGE Nº _____ 4.4 REDUNDANT FACTOR ASTRIONICS SYSTEM-COMMAND & CONTROL IMPORTANCE FACTOR ITEM GRADE FACTOR FACTOR ASSESSMENT ITEM ITEM DESCRIPTION GRADE METHOD Command Functions Adequacy Functions Verification Assessment 2 Command Status Functions Monitoring 3 Adequacy Command-Verification time Lag 4 Penalty Assessment Antenna Remote Control 5 Adequacy Assessment Development Risk Assessment 6 7 Total Power Requirement Assessment 8 Weight Assessment Cost Assessment 9 10 11 12 13 14 15 16 17 18 19 20

	GRADE	TOTAL:
GRADE=(GRADE	TOTAL) + (Nº OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

5.1

PAGE Nº 2

CIENT	IFIC FOUIP - ESS FOUIPMENT	REDUNDA	NT FA	CTOR	
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Tidal Gravimeter Adequacy				
2	Quake Seismometer Adequacy				
3	Star Tracker Adequacy				
4	Lunar Ejecta Spectrometer Adequacy				
5,	Solar Plasma Spectrometer Adequacy				
6	Magnetometer Adequacy				
7	Charged Particle Spectrometer Adequacy				
8	Gama Ray Detector Adequacy				
9	Neutron Phoswich Detector Adequacy				
10	Atmosphere Mass Spectrometer Adequacy				
11	Total Gas Press. Gauge Adequacy				
12	Charged Dust Spectrometer Adequacy				
13	Lunar Atmosphereic Hydrogen, Lyman-Alp Detector Adequacy	ha			
14	Permanent Thermal Probe Adequacy				
15	Telecommunications Sys. Adequacy				
16	Power Supply Adequacy				
17	Antenna Adequacy				
18	Materials Compatibility with Lunar Environment Assessment				
19	Weight Assessment				
20	Cost Assessment				
		GPADE	707	<u> </u>	

	GRADE TOTAL:
	GRADE=(GRADE TOTAL) - (Nº. OF ITEMS):
(GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR):

5.2

PAGE Nº . TT

SCIENTIFIC EQUIP_-INSTRUMENTS_FIXED VEHICLE
IMPORTANCE FACTOR

METHOD FACTOR FA T. V. Camera Coverage Adequacy Theodolite Location Adequacy	RADE CTOR	GRADE
T. V. Camera Coverage Adequacy 2 Theodolite Location Adequacy		
G i da C antinal Adamsu		
Gravimeter Operational Adequacy		
3 Gravimeter Operational Adequacy		
Seismic Survey Instrumentation Adequacy		
5 Magnetometer, Boom Mt. Adequacy		
6 Interferometer Operational Adequacy		
7 Mass Spectrometer (Solids) Adequacy		
8 X-Ray Diffractometer Oper. Adequacy		
9 Drill (6.1 M. Depth) Mounting Adequacy		
NO Drill (30.5M. Depth) Mounting Adequacy		
Sample Collection & Preservation Assessment		
Spectrometer Refraction Grating Type Operational Adequacy		
13 Ejecta Detector Assessment		
Lunar Environment Exposure Panel Assessment		
Total Radiation Dosimeter Assessment		
Total Power Requirement Assessment		
17		
18		
19		;
20		

·	GRADE	101AL:
GRADE=(GRADE	TOTAL) - (Nº. OF	TEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTANC	E FACTOR):

5.3

PAGE Nº.___

ENTII	FIC EQUIP INSTRUMENTS, PORTABLE	REDUNDA	NT FA	CTOR	
		IMPORTANO	CE FA	CTOR	
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRA
1	T.V. Camera Operational Assessment				
2	Theadolite Operational Assessment				
3	Electric Field Meter Assessment				
4	Charged Dust Spectrometer Assessment				
5	Temperature Profile, Thermal Conductivit & Diffusivity Instruments Adequacy	У			
6	Gamma-Ray Densitometer Assessment				
7	Electrical Measurement Instru. Adequacy				
8	Acoustic Velocity Instru.				
9	Radio Activity Probe, Radio Activity Detec (Alpha; Beta, Gamma) Assessment	tor			
10	Neutron Gamma-Ray Detector Assessment				
11	Alpha Particle Mass Spectrometer Assessr	nent			
12	Gas Chromatograph Oper. Assessment				
13	Geophysical Subsurface Probe Adequacy				
14	Mass Spectrometer, Atmospheric Gas, Assessment				
15	Total Gas Press; Gauge Adequacy		•	,	
16	Photographic Cameras Adequacy				
۱٦	Total Power Requirement Assessment				
18					
19					
20					

GRADE TOTAL: ____ GRADE = (GRADE TOTAL) ÷ (Nº: OF ITEMS) : ____ (GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR): ____

6.1

PAGE NO.

		DEDUNDANT	ENCTOR
UNLOADING & TIEDOWN	SYSSUPPORTS	& TIEDOWN CHUAN	IACIUR
		11.400071.105	

<u> </u>		IMPORTANCE FACTOR			
ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
1	Chassis Support Structure Adequacy				
,2	Chassis Support Load Path Simplicity				
3	Wheel Support Structure Adequacy				
4	Wheel Support Load Path Simplicity				
5.	Chassis Support Deployment Adequacy				
6	Chassis Support Reliability Assessment				
7	Chassis Supt. Deployment Shock Assessme	nt			
8	Wheel Support Deployment Adequacy				
9	Wheel Support Reliability Assessment				
10	Wheel Supt. Deployment Shock Assessmen				_
11	Supt's Deployment at Max. Tilt Assessmen	it			
12	Ordinance Devices Safety Assessment	-			
13	Materials Compatibility with Lunar Environment				
14	Development Risk Assessment				
15	Weight Assessment				
16	Cost Assessment				
17	Total Power Requirement Assessment				
18	·				
19					
20					
				1	

GRAU	DE 10	1AL:
GRADE = (GRADE TOTAL) + (Nº. (OF ITE	EMS):
(GRADE) × (REDUNDANT FACTOR × IMPORT	TANCE	FACTOR):
		•

6.2

PAGE NE __

	6.2		PAGE	. Nº.			
INLOADING & TIEDOWN SY'S-VARIABLE AZIMUTH DEVICE FACTOR							
ITEN	TEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE		
1	Loaded Operational Capability Assessment		-				
2	Selected Azimuth Accuracy Assessment						
3	Structural Simplicity Assessment						
4	Operational Characteristics at Max. Deck Tilt Assessment.						
5	Azimuth Holding Ability Assessment						
6	Azimuth Selection Efficency Assessment						
7	Mechanism Seals Capability Assessment						
8	Materials Compatibility with Lunar Fhviron	1.					
9	Development Risk Assessment						
10	Weight Assessment						
11	Cost Assessment						
12	Total Power Requirement Assessment						
13							
14							
15							
16							
17							
			:	1	1		

,	GRADE	TOTAL:
GRADE=(GRADE	TOTAL) + (Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

18

19

20

6.3

PAGE Nº ____

ADING	3 & TIEDOWN SYS DEPLOYMENT	REDUNDA	NT FA	CTOR	
		IMPORTANI	CE FA	CTOR	
IĨĒM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	9
í	Ramps Extension, Any Azimuth Capability Assessment				
2	Ramps Load Capacity Adequacy Assessmer	.t			
3	Ramps Extension at Max. Deck Tilt Angle Capability Assessment	•			
4	Ramps Lunar Contact Angle Adequacy Assessment				
5	Ramps Extension Dimensional Adequacy			•	
6	Ramps Retracted Dimensional Adequacy		,		Ī
7	Manual Unloading Capability Assessment				T
8	Remote Command Track Extension Efficency Assessment		£		T
9	MOLAB Unloading LEM-T Clearance Assessment				
	MOLAB Unloading Nose Clearance Lunar Surface Assessment				
11	Materials Compatability with Lunar Environment				
12	Development Risk Assessment				
13	Stability of MOLAB During Unloading	·			
14	Stability of LEM-T During Unloading Assessment				
	MOLAB unloading Velocity Adequacy Assessment				
16	MOLAB Unloading Velocity control Adequa Assessment	су			
17	Weight Assessment				
18.	Cost Assessment				
19	Total Power Requirement Assessment				
20					

GRADE = (GRADE TOTAL) + (Nº. OF ITEMS) : _ ___ (GRADE) × (REDUNDANT FACTOR × IMPORTANCE FACTOR): _ ___

PAGE Nº Y

UNLOADING & TIEDOWN SYS. -ELECTRONIC EQUIP.

IMPORTANCE FACTOR

ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE FACTOR	GRADE
ſ	Unloading Sequence Programmer Adequacy Assessment				
2	Sequence Command Capability Assessment				
3	Sequence Arming Adequacy Assessment				
4	Sequence Command Verification Assessment	nt			
5	T.V. Surface Condition Capability Assess	nent			·
0	Electrical Power Adequacy Assessment				
7	MOLAB Unload Velocity Monitor Adequacy Assessment				
8	Telemetry Verification Monitoring Adequacy Assessment				
9	Materials Compatability with Lunar Environment	on.			
10	Development Risk Assessment				
11	Weight Assessment				
12	Cost Assessment				
13	Total Power Requirement Assessment				
14	•				
15					
16		•			
17		·			
18					
19					
20					

		TOTAL:
GRADE=(GRADE	TOTAL) + (Nº. OF	ITEMS):
(GRADE) × (REDUNDANT	FACTOR × IMPORTAN	CE FACTOR):

MOLAB VEHICLE

ITEM	ITEM DESCRIPTION	ASSESSMENT METHOD	ITEM FACTOR	GRADE	ITEM GRADE
1	Cabin Radiation Shielding Adequacy Assessment				
2	Cabin Micro-Meteroroid Protection Adequacy Assessment	·			
3	Cabin EMI Emissivity Adequacy Assessment				
4	Cabin Leakage Detection System Adequacy Assessment				
5	Cabin To Lunar Surface Access Adequacy Assessment			-	
؈	Docking Guide Adequacy				,
7	Docking Instrumentation Adequacy				
8	Docking Securing Adequacy				
9	View Port Locations Adequacy				
10	MOLAB Astronauts Command Post Adequa	су		·	
11	MOLAB Ground Clearence Adequacy				
12	Step Negotiability Assessment				
13	Crevice Negotiability Assessment				
14	Max. Assending Slope Negotiability Assessment				
15	Max. Decending Slope Negotiability Assessment				
16	Negotiability Range of Soil Softness Assessment				·
۱7	Maximun Vehicle Range, Hard Soil, Capability Assessment				
18	Maximun Vehicle Velocity, Hard Soil, Assessment				`
19	Braking Adequacy, Dynamic & Static, Assessment				
20	Vehicle Turning Radius Adequacy				

DΔ	GE	Nº.	
	125	177-	

MOLAB VEHICLE

ITEM	SYSTEM	IMPORT.	RATING
21	Vehicle Ride Control Adequacy		·
22	Vehicle Performance Capabiltiy Assessment for all Mission Phases		
23	Mass Properties Optimizations Assessment		
24	External Equip. Micrometeroid Protection Adequacy		
25	External Equip. Thermal Protection Adequacy		
26	External Storage of Scientific Equip. Adequacy	_	
27	Maintainability of Externally Mounted Equipment Assessment		
28	MOLAB/Unloader, LEM-T Umbilical Fouling Hazard Assessment		
29	MOLAB/Scientific Equip. Umbilicals Accessability Assessment		
30	MOLAB Outside Astrounaut Umbilical Utilization Assessment		
31	Space Suit Damage from MOLAB Projections. Probability Assessment		
32	Development Risk Assessment		
33	Total Weight Assessment		
34	Total Vehicle System Cost Assessment		
35	Total Vehicle Power Requirements Assessments		
36	MOLAB/LEM-T Integration Adequacy Assessment		
37	MOLAB/Ground Support Equipment Integration Adequacy		
38	MOLAB/Saturn & Apollo CSM Integration Adequacy		
95			
40			

GRADE = (GRADE TOTAL : Nº OF ITEMS): ____

PAGE NO 32

MOLAB VEHICLE

ITEM	SYSTEM	IMPORT. FACTOR	GRADE	RATING
1	Cabin System - Structural (1.1)			
2	Cabin System - Airlock (1.2)			
3	Cabin System - Docking Adapter (1.3)			
4	Cabin System - Viewing Ports (1.4)			-
5	Cabin System - Controls & Display (1.5)			
8	Cabin System - Crew Systems (1.6)			
7	Cabin System - Environmental Control Sys. (1.7)			
8	Mobility System - Chassis (2.1)			
9	Mobility System - Cryogenic Storage (2.2)			
10	Mobility System - Drive Mechanism (2.3)			
111	Mobility System - Wheel Assembly (2.4)			
12	Mobility System - Suspension Assy (2.5)			
13	Mobility System - Steering Mechanism (2.6)			
14	Power System - Primary Power (3.1)			
. 15	Power System - Secondary Power (3.2)			
16	Power System - Auxiliary Power (3.3)			
17	Power System - Power Distribution (3.4)			
18	Power System - Heat Dissipation (3.5)			
19	Astridnics system-Navigation and Guidance (4.1)			
20	Ástrionics system-Communication (4.2)			

PAGE Nº. ____

ITEM	SYSTEM	IMPORT.	GRADE TOTAL	RATING
21	Astrionics System - Electronics (4.3)			
22	Astrionics System - Command & Control (4.4)			
23	Scientific Equip - ESS Equipment (5.1)			
24	Scientific Equip - Instruments, Fixed Vehicle (5.2)			
25	Scientific Equip - Instruments, Portable (5.3)			
26	Unloading & Tiedown systems - Support & Tiedown (6.1)			
27	Unloading & Tiedown Systems - Var. Azimuth Device (6.2)			
28	Unloading & Tiedown Systems - Deployment (6.30			
29	Unloading & Tiedown Systems - Electronic Equipment (6.4)			
30	Concept Rating Sheet Total			
31				
32				
33				
34				
35				
36				
37				
38				
39				
40	·			

CONCEPT COMPARISON RATING: ____

DISTRIBUTION

INTERNAL

R-DIR

H. K. Weidner

DEP-T

R-AERO-DIR

-S

-SP (23)

R-ASTR-DIR

-A (13)

R-P& VE-DIR

-A

-AB (15)

-AL(5)

R-RP-DIR

-J(5)

R-FP-DIR

R-FP (2)

R-QUAL-DIR

-J (3)

R-COMP-DIR

R-ME-DIR

-X

R-TEST-DIR

I-DIR

MS-IP

MS-IPL (8)

EXTERNAL

NASA Headquarters

MTF Col. T. Evans

MTF Maj. E. Andrews (2)

MTF Mr. D. Beattie

R-1 Dr. James B. Edson

MTF William Taylor

Kennedy Space Center

K-DF Mr. von Tiesenhausen

Northrop Space Laboratories

Huntsville Department

Space Systems Section (5)

Scientific and Technical Information Facility

P.O. Box 5700

Bethesda, Maryland

Attn: NASA Representative (S-AK RKT) (2)

Manned Spacecraft Center

Houston, Texas

Mr. Gillespi, MTG

Miss M. A. Sullivan, RNR

John M. Eggleston

C. Corington, ET-23 (1)

William E. Stanley, ET (2)

Donald Ellston

Manned Lunar Exploration Investigation

Astrogeological Branch

USGS

Flagstaff, Arizona

Langley Research Center

Hampton, Virginia

Mr. R. S. Osborn